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國立臺灣大學101學年度碩士班招生考試試題

科目:應用數學(A)

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※ 注意:請於試卷內之「非選擇題作答區」作答,並應註明作答之題號

## I. Fill in the blanks:

- 1. {15 points} Which of the following statements are true? Answer: \_\_\_
  - (a) If  $\vec{x}$  is a nonzero vector and  $\vec{0}$  the zero vector in  $\mathbb{R}^n$  such that  $A\vec{x} = \vec{0}$ , then the determinant of the  $n \times n$  matrix A is vanishing.
  - (b) The set of vectors  $\{(1,2,4)^T, (2,1,3)^T, (4,-1,1)^T\}$  span the vector space  $\mathbb{R}^3$ .
  - (c) If the vectors  $x_1, x_2, ..., x_n$  span a vector space  $\mathbb{V}$ , then they are linearly inde-
  - (d) If S and T are subspaces of a vector space  $\mathbb{V}$ , then the union  $S \cup T$  is also a subspace of V.
  - (e) If the  $n \times n$  matrix  $A \neq O$  (where O denotes the zero matrix) but  $A^k = O$  for some positive integer k, then A must be singular.
- 2. {15 points} Using LU factorization, the matrix A can be written as

$$A = \begin{pmatrix} 1 & 2 & 1 & 2 \\ 2 & 0 & 2 & 1 \\ 2 & 3 & 1 & 3 \\ 1 & 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 2 & 1/4 & 1 & 0 \\ 1 & 1/2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 & 2 \\ 0 & -4 & 0 & -3 \\ 0 & 0 & -1 & -1/4 \\ 0 & 0 & 0 & 1/2 \end{pmatrix} \equiv LU$$

- (a) The determinant det(A) =
- (b) The solution of  $A\vec{x} = (1, 1, 1, 1)^T$  is  $\vec{x} = (x_1, x_2, x_3, x_4)^T =$ Note that here the superscript T denotes transpose.
- (c) The third column of  $A^{-1}$  (expressed as a column vector) =
- 3.  $\{10 \text{ points}\}\$ Consider the  $2 \times 2$  matrix

$$A = \begin{pmatrix} a & 1 \\ \gamma & \delta \end{pmatrix}.$$

- (a) To make A possess eigenvalues  $\lambda = 1$  and  $\lambda = -1$  for any given value of a, one must choose  $\gamma$  and  $\delta =$  \_\_\_\_\_
- (b) To make the eigenvectors corresponding to  $\lambda = 1$  and  $\lambda = -1$  orthogonal, a must be chosen to be \_\_\_\_\_

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4. {10 points} Let

$$\vec{b}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{b}_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \quad \vec{b}_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

and let L be the linear transformation from  $\mathbb{R}^2$  to  $\mathbb{R}^3$  defined by

$$L(\vec{x}) = x_1 \vec{b}_1 + x_2 \vec{b}_2 + (x_1 + x_2) \vec{b}_3 \qquad \forall \, \vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2.$$

If A is the matrix representing L with respect to the bases  $\{\vec{e}_1, \vec{e}_2\}$  and  $\{\vec{b}_1, \vec{b}_2, \vec{b}_3\}$ , where

 $ec{e}_1 = \left(egin{array}{c} 1 \ 0 \end{array}
ight), \quad ec{e}_2 = \left(egin{array}{c} 0 \ 1 \end{array}
ight),$ 

then  $A = \underline{\hspace{1cm}}$ .

## II. Calculation problems:

5.  $\{10 \text{ points}\}$  With y = y(x) being a function of the independent variable x, solve the differential equation

$$\frac{d^3y}{dx^3} + 2\frac{d^2y}{dx^2} + \frac{dy}{dx} = 3e^x.$$

6.  $\{20 \text{ points}\}$ With y = y(x) being a function of the independent variable x, solve the differential equation

$$\frac{d^2y}{dx^2} + 8x\frac{dy}{dx} + (16x^2 + 4 + \frac{1}{4x^2})y = 4e^{-2x^2}.$$

7.  $\{20 \text{ points}\}$ With y = y(x) being a function of the independent variable x, solve the differential equation

$$4x\frac{d^2y}{dx^2} + 2\frac{dy}{dx} + 2y = 1.$$

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